

FEATURE LIST

	Features		Advantages
INPUTS	Pix4Dmapper project		Seamless import of processed Pix4Dmapper projects (.p4d). Start the vectorization using original images and generated point cloud
	Point clouds	-	Import point clouds created with photogrammetry, laser scanners, LiDAR or other third-party tool in .las or.laz format
TOOLS AND FUNTIONS	Easy to use interface		An intuitive interface with a short learning curve for a fast integration into existing workflows
	Layers	-	Manage the vectorized data in layers. Easily move objects between layers
	Properties	-	See properties and measurements of any object
	Shortcuts	-	Integrated shortcuts for faster navigation and vectorization
	Project visualization	-	Display vectorized geometry and point clouds in the same context
	Point cloud display	-	Fast and lightweight point cloud display optimized for large projects
	Camera display	-	Display the calibrated position of original images in the 3D view
	Vectors objects display in orignal images	Ģ	Vectorized objects appear in both 3D and in the original images
VECTORIZATION	Create markers	-	Quickly vectorize individual objects, for example manholes, poles or trees to mark and inspect
	Create polylines	-	Ideal for vectorizing linear objects, for example roads, curbs, fences and breaklines
	Create polygons	-	Ideal for vectorizing polygons, for example building footprints and roofs
	Create catenary curves	Ţ	For optimal vectorization of freely hanging power lines
EDITING	Editing in 3D	Ģ	Edit the position of the point by simply dragging it to the desired position in 3D
	Editing in 2D	-	Take advantage of original images to precisely place points
	Vertex editor	-	Enter the desired coordinates of points manually or copy-paste a known position
3D OUTPUT	Export to .dxf	-	Export all or a single layer to a .dfx file
LANGUAGE	Language option	-	English

HARDWARE SPECS



CPU: Quad-core or hexa-core Intel i7/Intel i9/Threadripper/Xeon







RAM: 32GB





OS: Windows 10, 64 bits or macOS Mojave

